

Cell Trajectory  
Inference based on  
Optimal Transport and  
a mechanistic  
stochastic gene  
expression model

Clémence FOURNIÉ

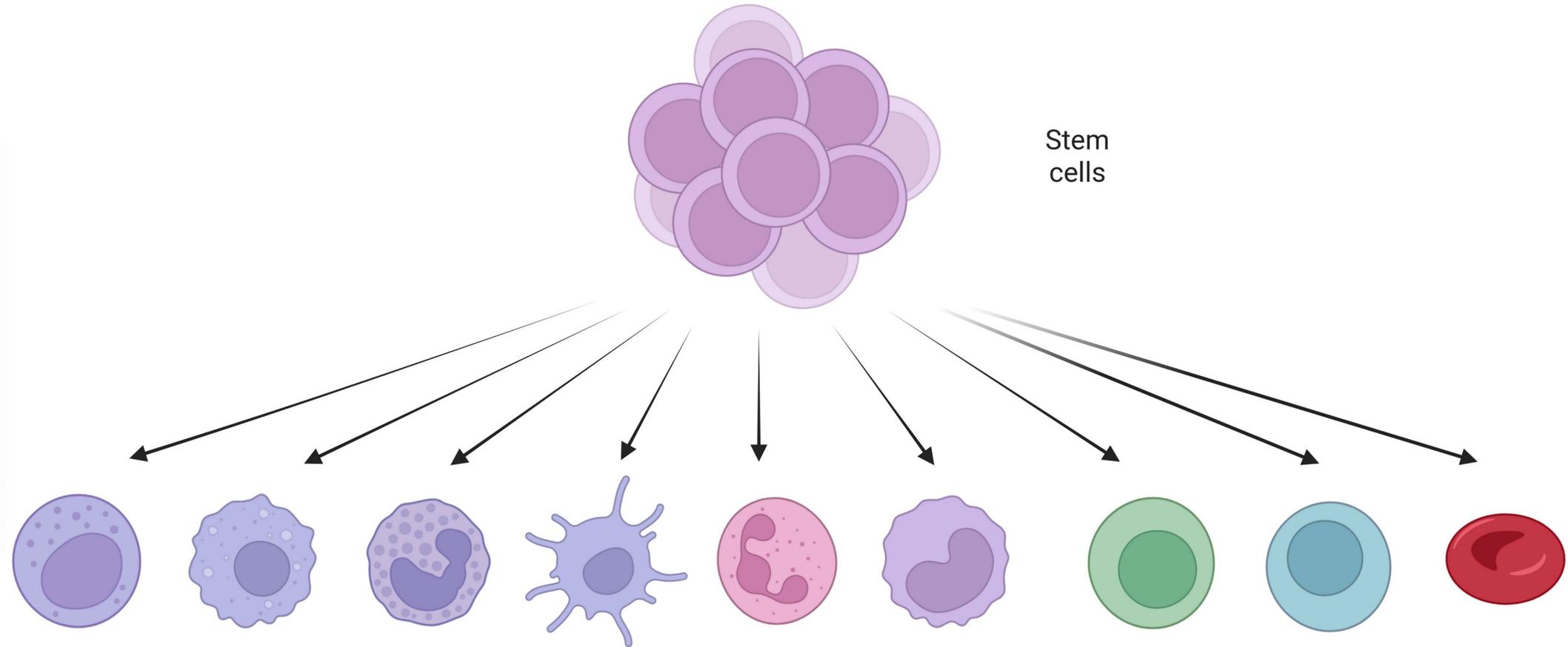
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In collaboration with Elias Ventre  
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(ICJ Lyon)

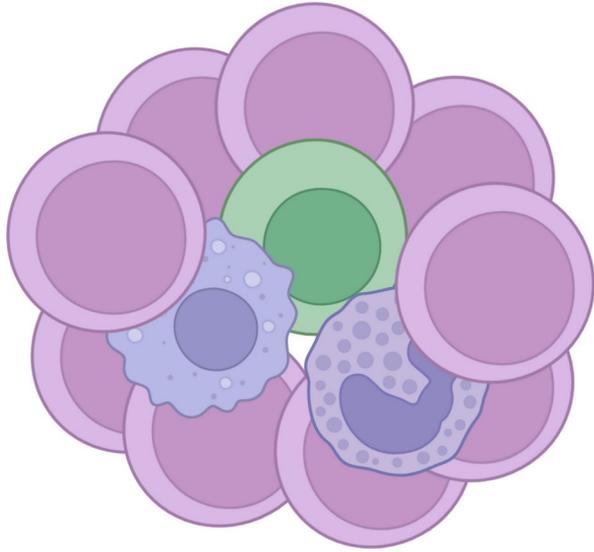
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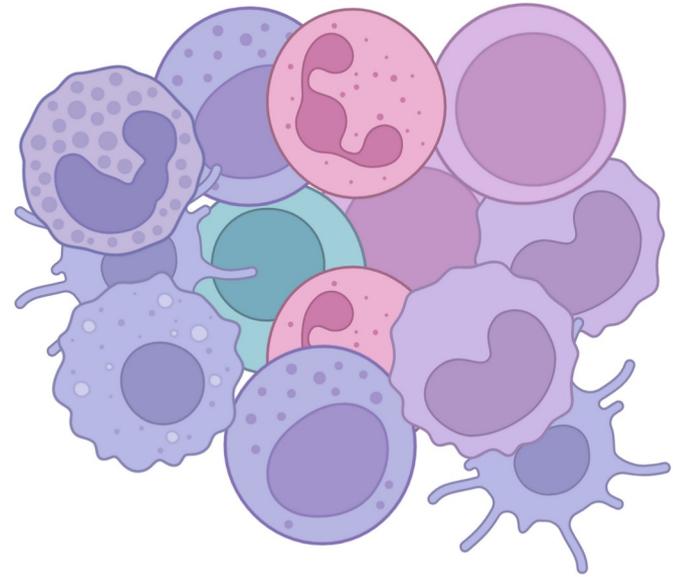
# Cellular differentiation



# Cellular differentiation



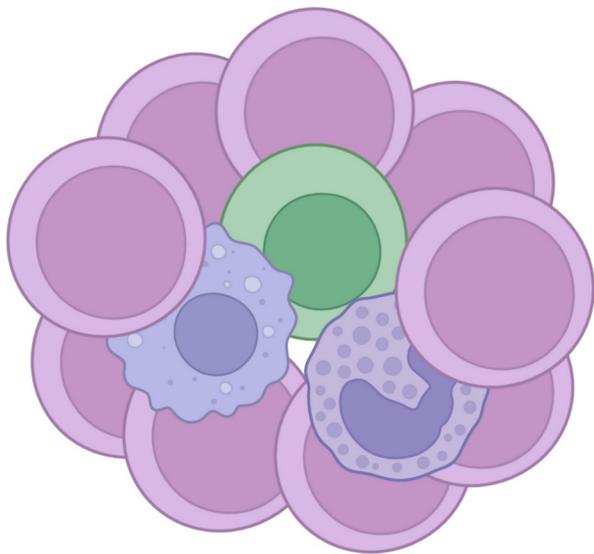
$t_1$



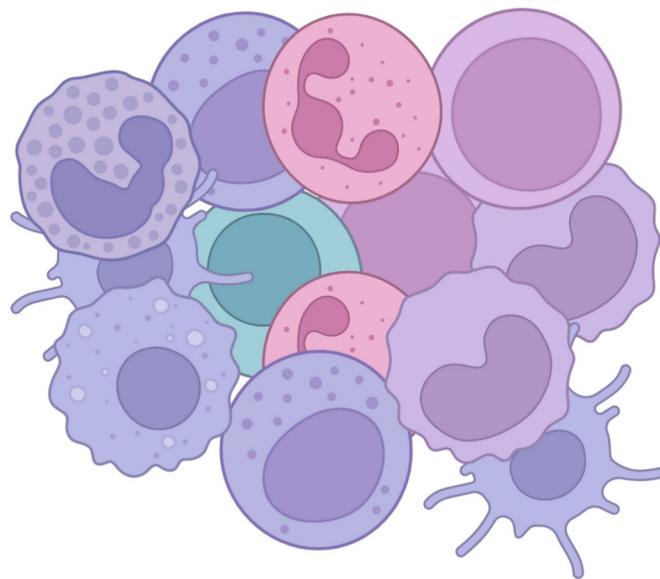
$t_2$

# Context

Experiment 1



Experiment 2

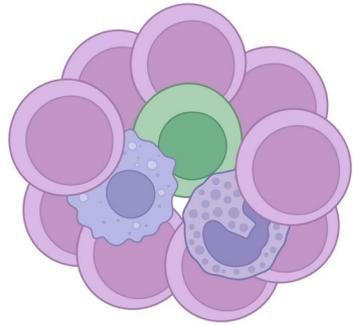


$t_1$

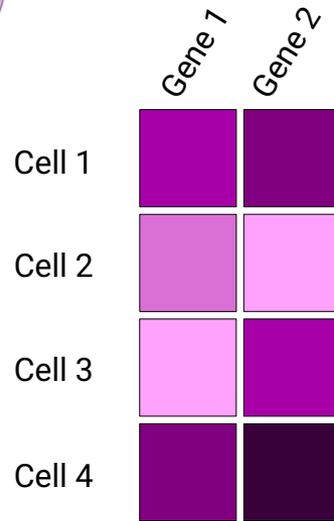
$t_2$



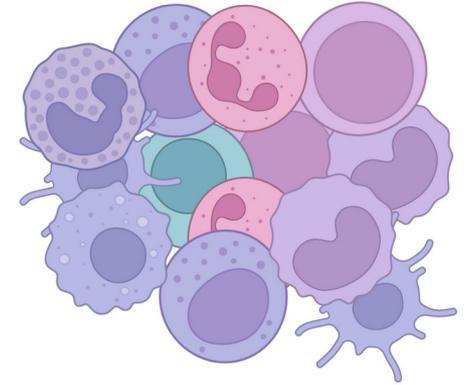
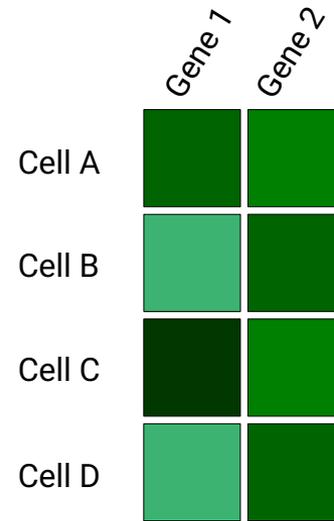
# Context



Experiment 1



Experiment 2

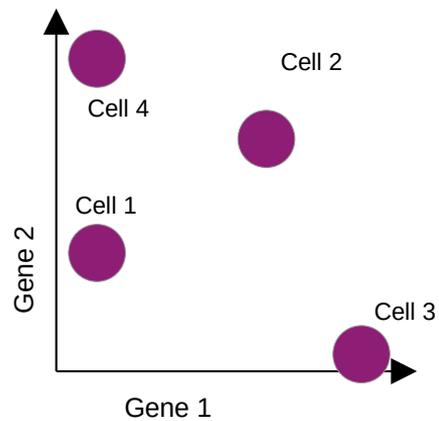


$t_1$

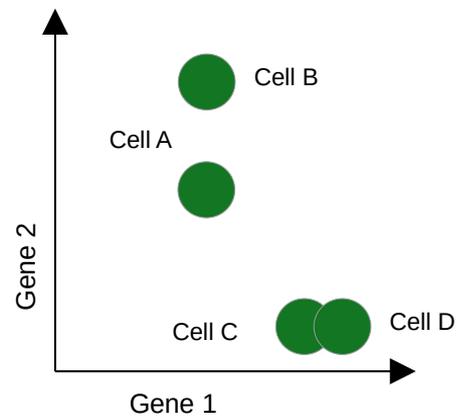
$t_2$

# Context

Experiment 1



Experiment 2



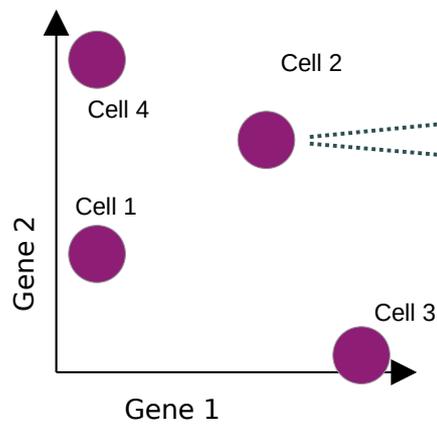
$t_1$

$t_2$

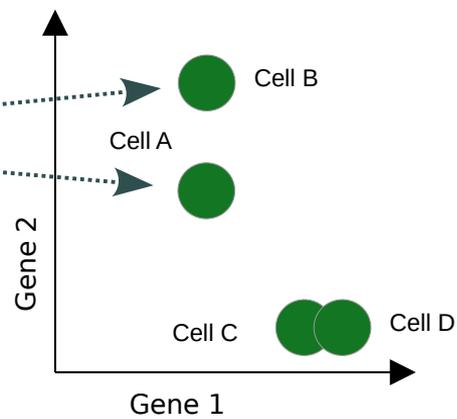


# Context

Experiment 1



Experiment 2



?

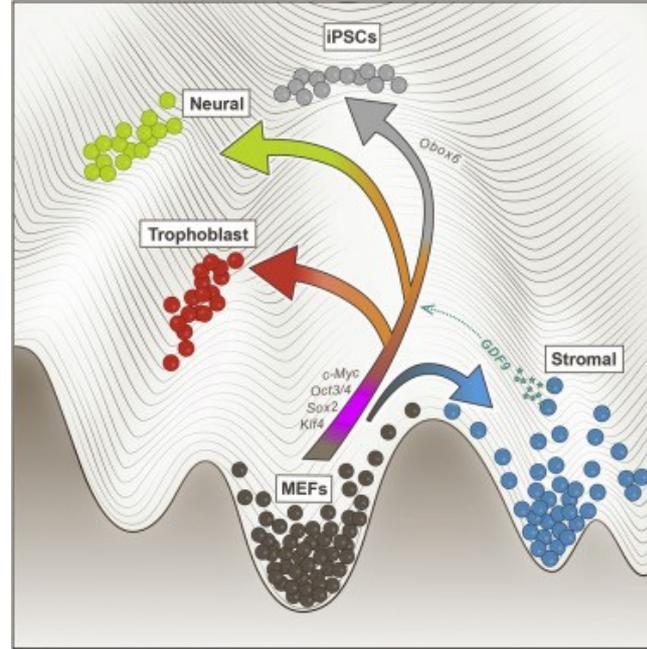
?

$t_1$

$t_2$

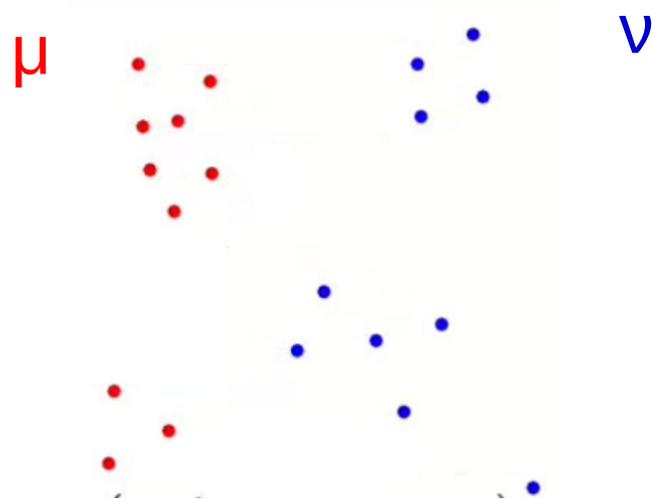


# Optimal Transport: WOT Algorithm



(Shiebinger et al. 2019)

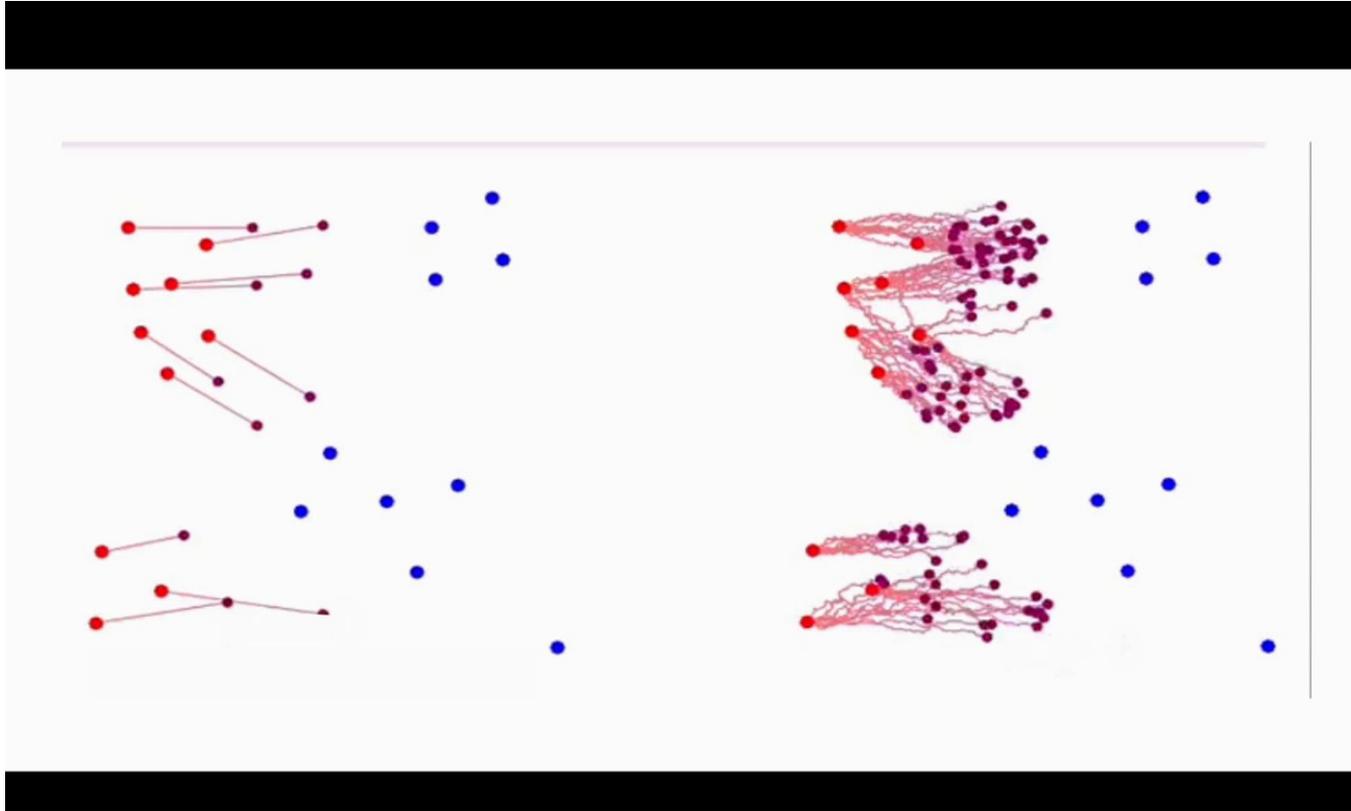
# Optimal Transport



# Methods: Schrödinger Problem

Optimal transport

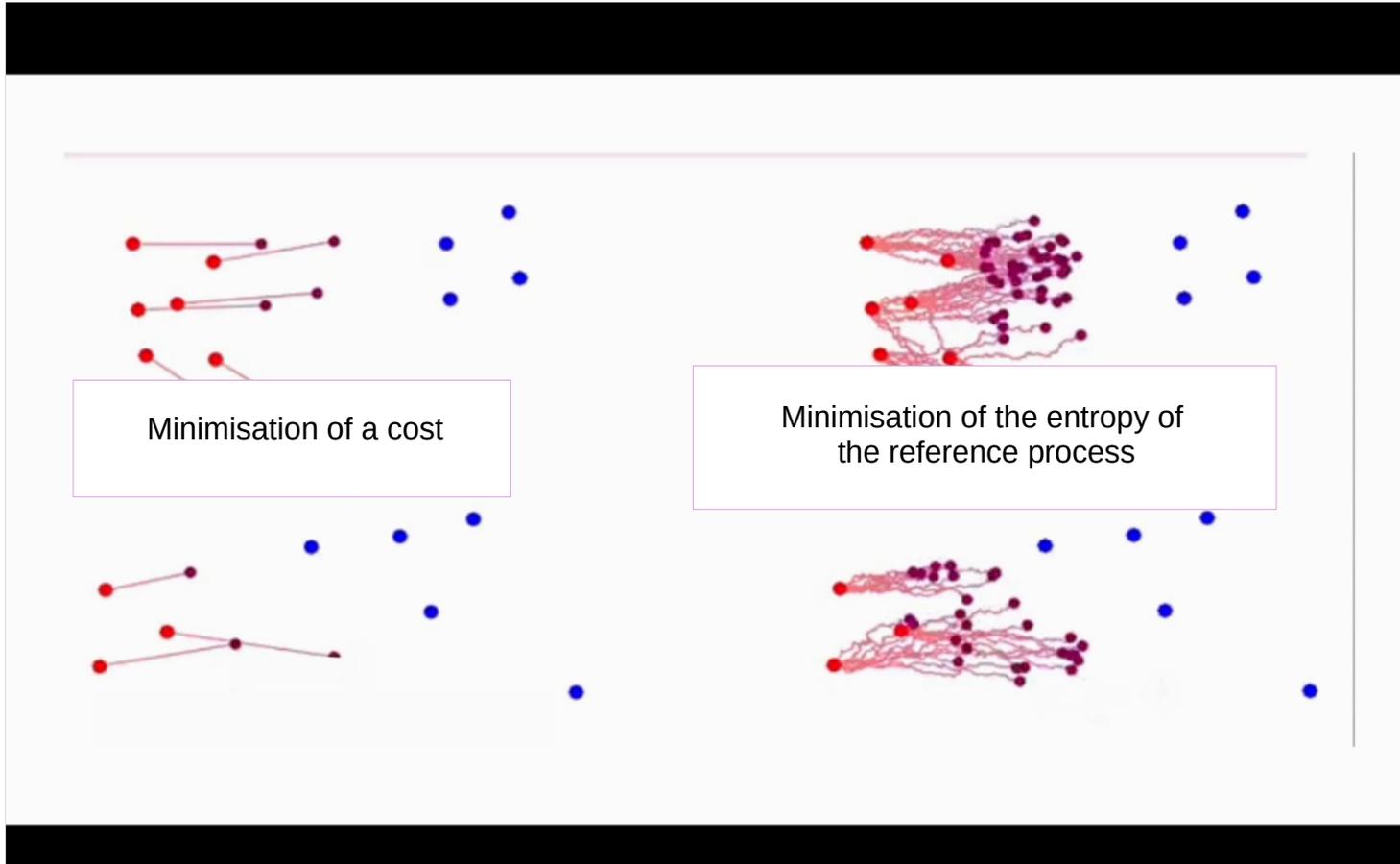
Schrödinger's Problem



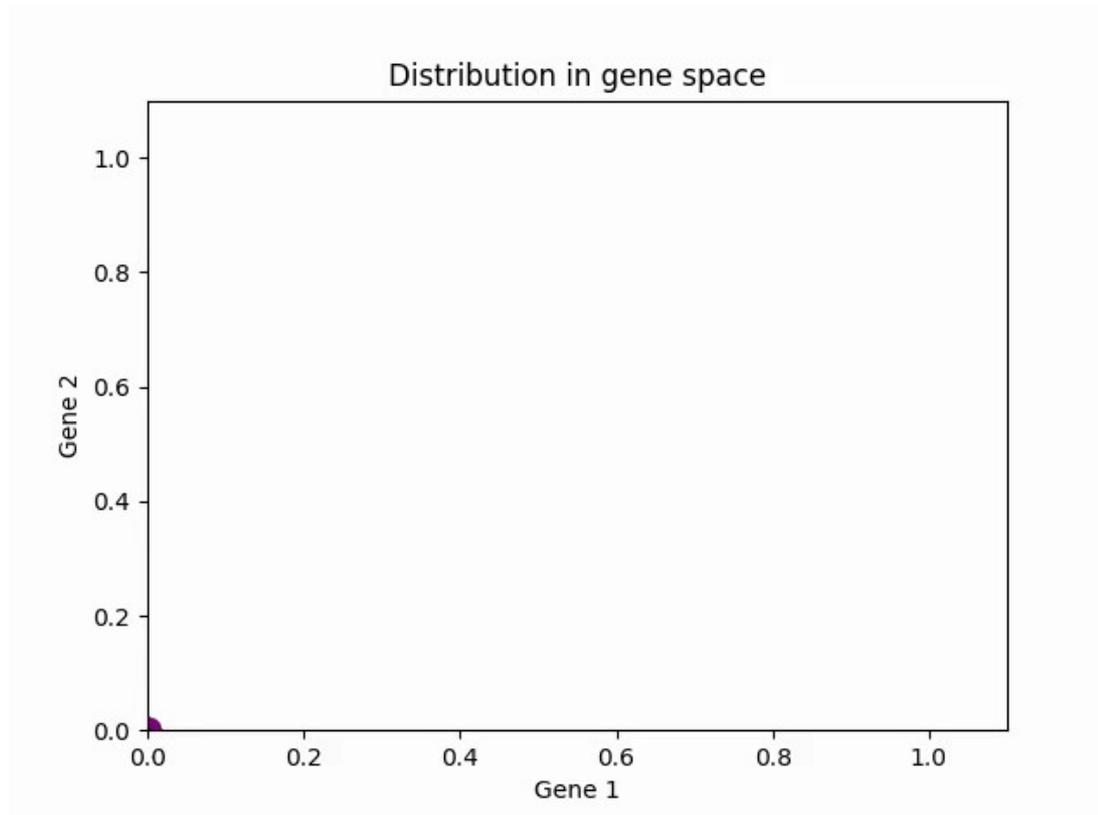
# Methods: Schrödinger Problem

Optimal transport

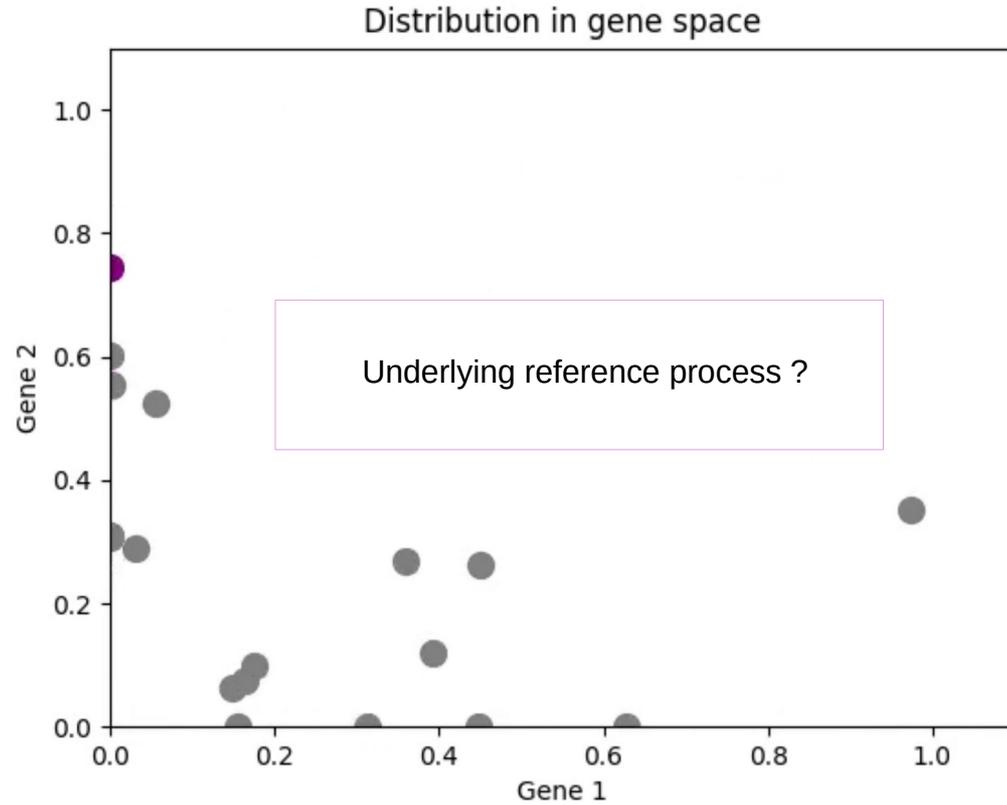
Schrödinger's Problem



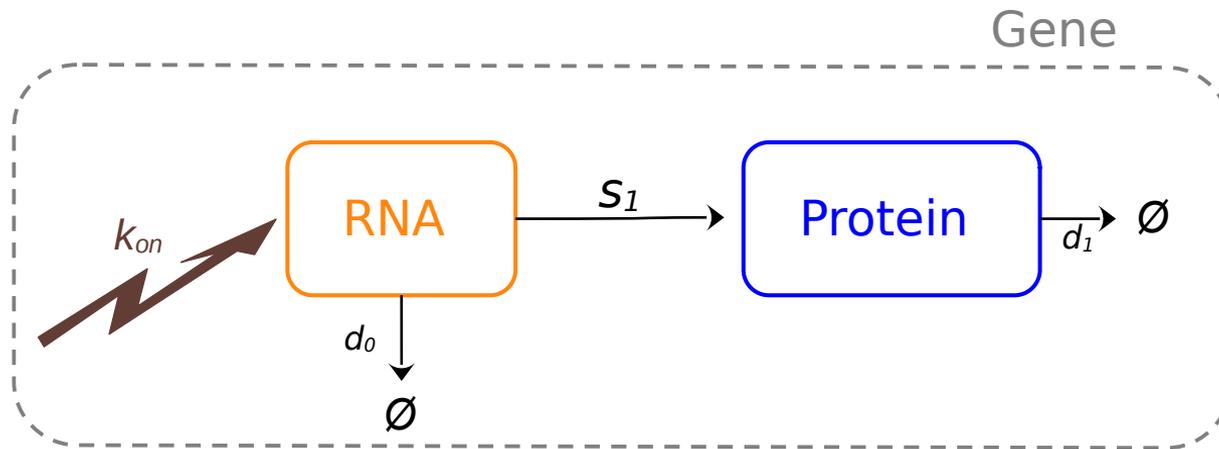
# Cells trajectories in 2D



# Cells trajectories in 2D



# Methods: Bursty Model



Piecewise-deterministic Markov process (PDMP) :

deterministic part

+

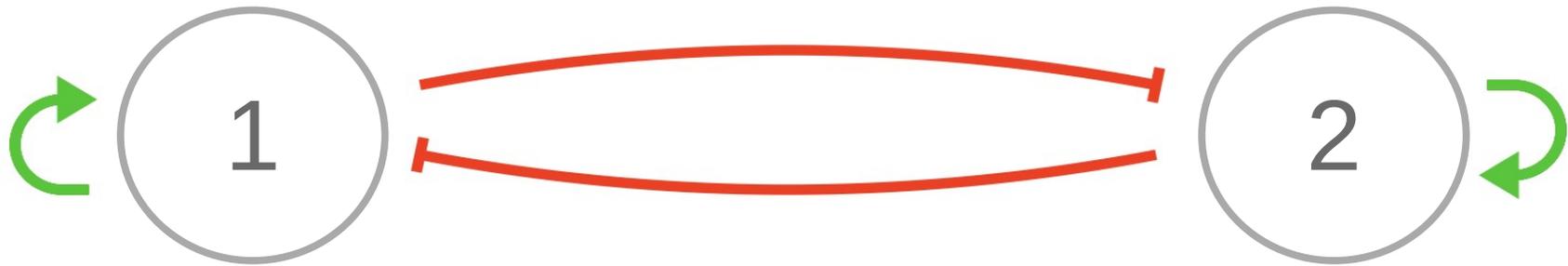
stochastic part

$$\begin{cases} \dot{M}(t) = -d_0 M(t), \\ \dot{P}(t) = s_1 M(t) - d_1 P(t) \end{cases}$$

$$k_{on}$$

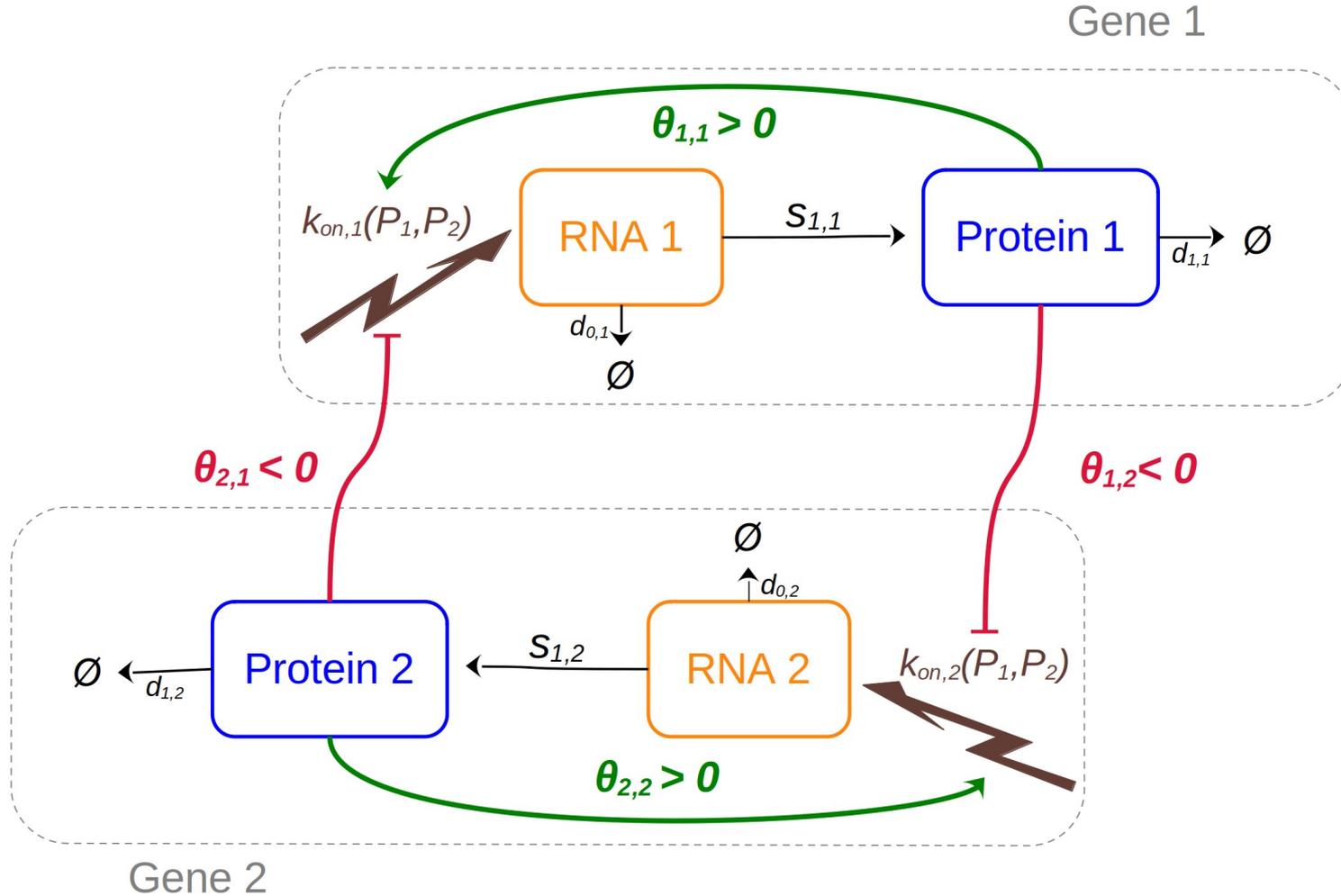
# Gene regulatory network (GRN) with 2 genes

## Toggle switch



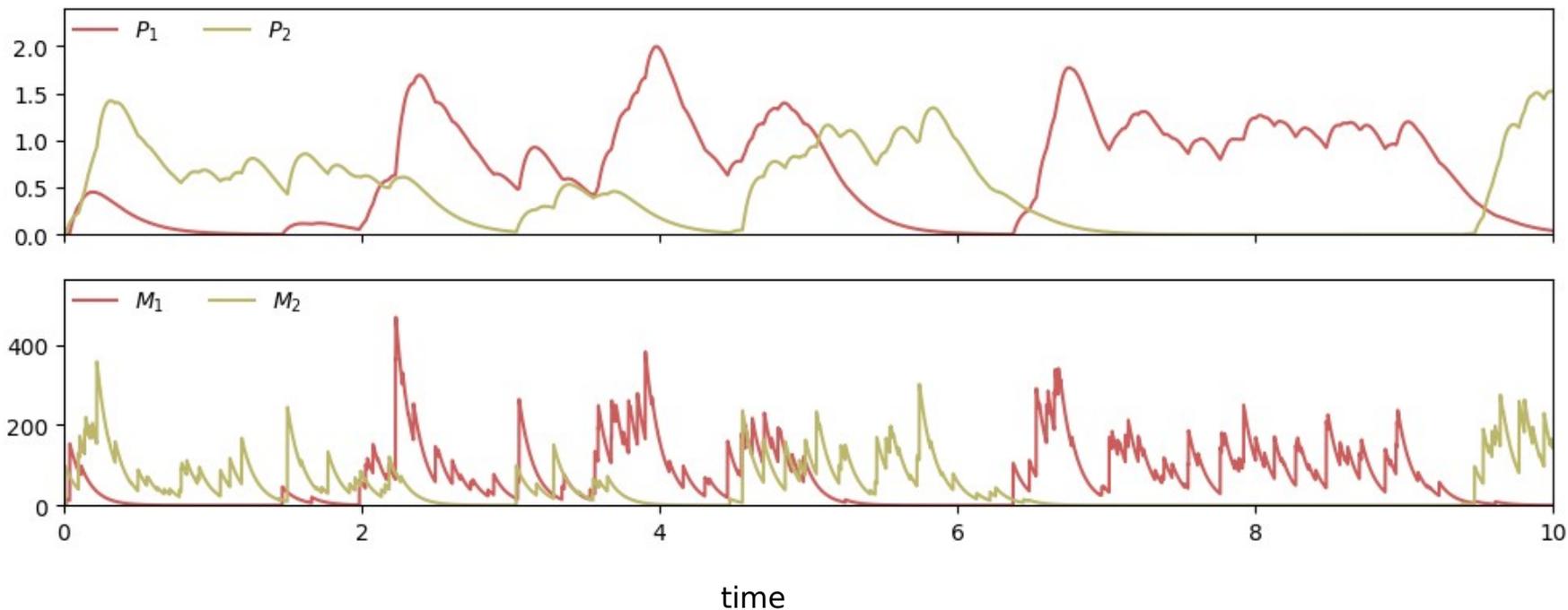
# Methods: Bursty Model

## Toggle Switch

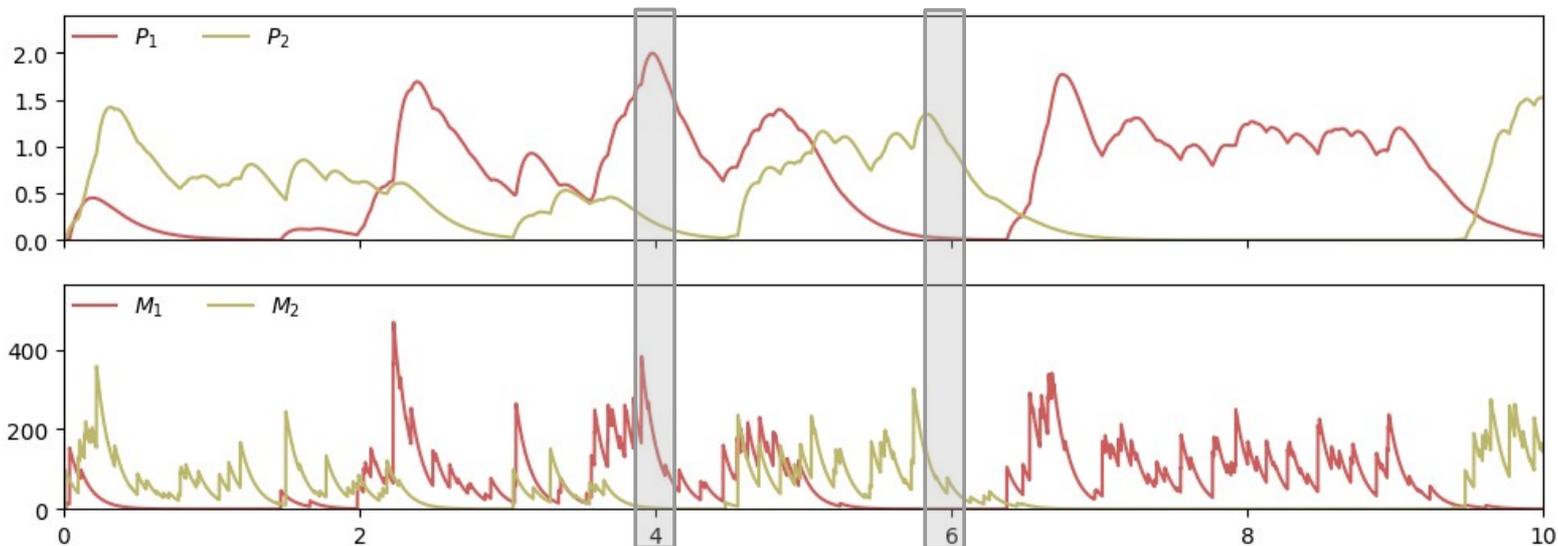


# Methods: Simulated data

Evolution of the two proteins (top) and RNA (bottom) quantities over time.  
Toggle switch Gene Regulatory Network. Results from HARISSA (Herbach, 2023).



# Methods: Simulated data



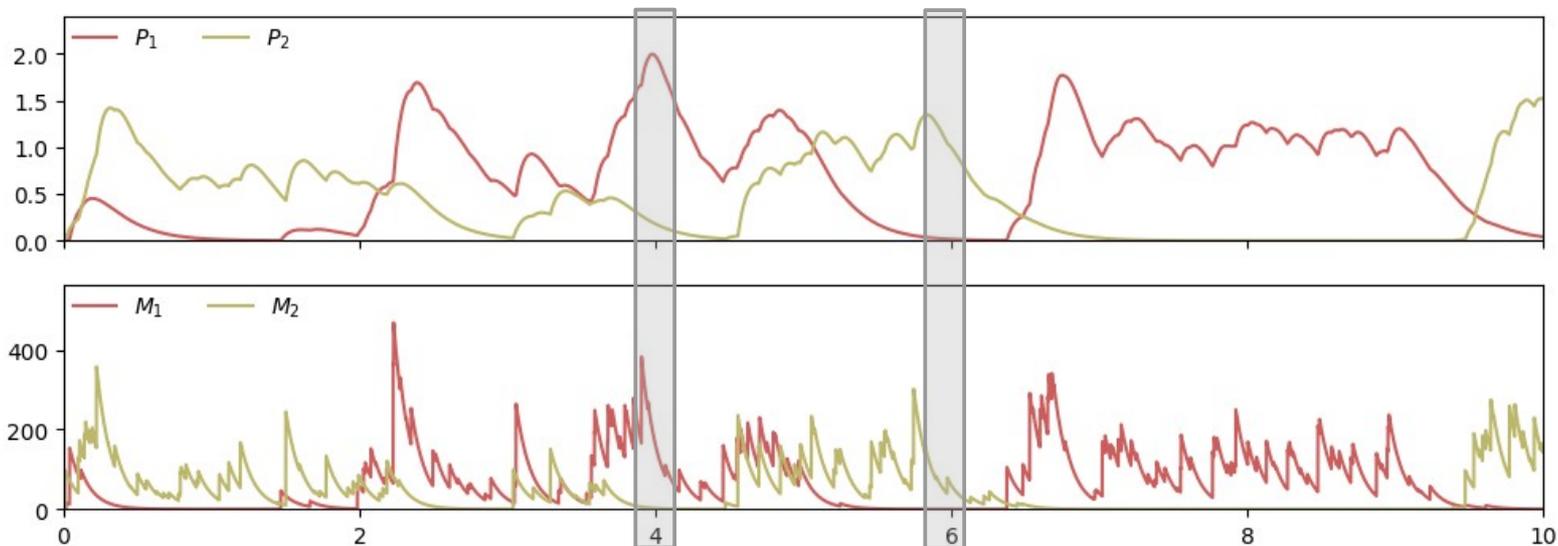
$$\begin{aligned} & \mathbf{t}_1 \\ \mathbf{x}_1 &= [(P_1, P_2), (M_1, M_2)] \\ & \cdot \\ & \cdot \\ \mathbf{x}_N &= [(P_1, P_2), (M_1, M_2)] \end{aligned}$$

$\mu$

$$\begin{aligned} & \mathbf{t}_2 \\ \mathbf{y}_1 &= [(P_1, P_2), (M_1, M_2)] \\ & \cdot \\ & \cdot \\ \mathbf{y}_N &= [(P_1, P_2), (M_1, M_2)] \end{aligned}$$

$\nu$

# Methods: Simulated data



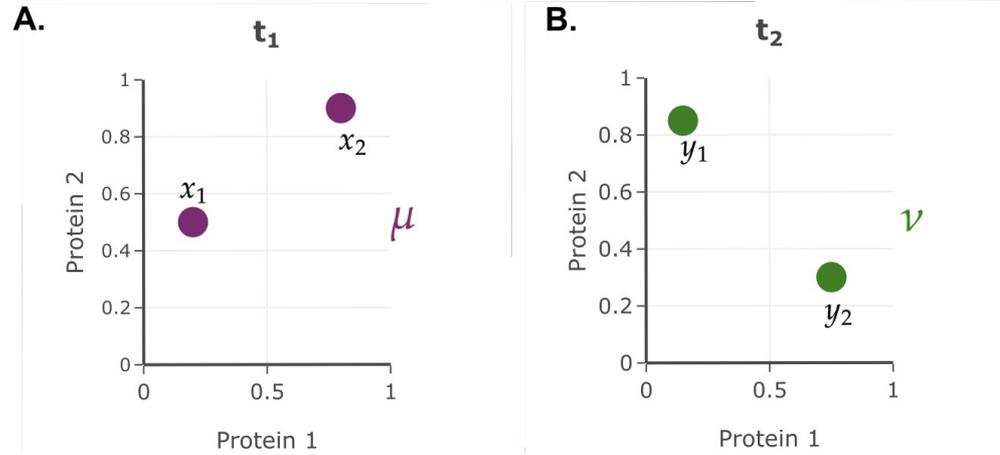
$$\begin{matrix} x_1 = \\ \vdots \\ x_N = \end{matrix} \begin{bmatrix} (P_1, P_2) \\ \vdots \\ (P_1, P_2) \end{bmatrix}, \begin{bmatrix} (M_1, M_2) \\ \vdots \\ (M_1, M_2) \end{bmatrix}$$

$\mu$

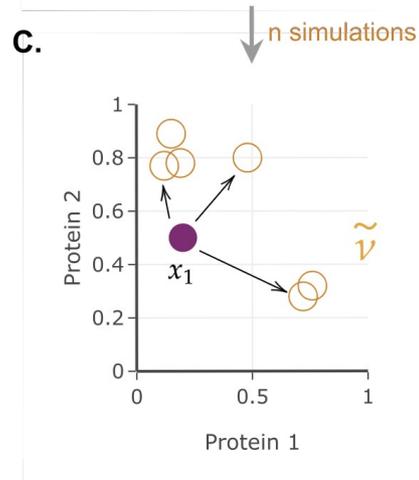
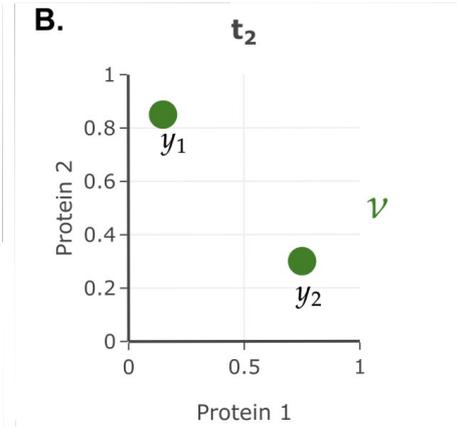
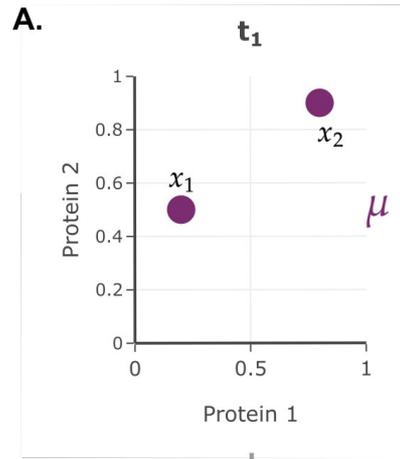
$$\begin{matrix} y_1 = \\ \vdots \\ y_N = \end{matrix} \begin{bmatrix} (P_1, P_2) \\ \vdots \\ (P_1, P_2) \end{bmatrix}, \begin{bmatrix} (M_1, M_2) \\ \vdots \\ (M_1, M_2) \end{bmatrix}$$

$\nu$

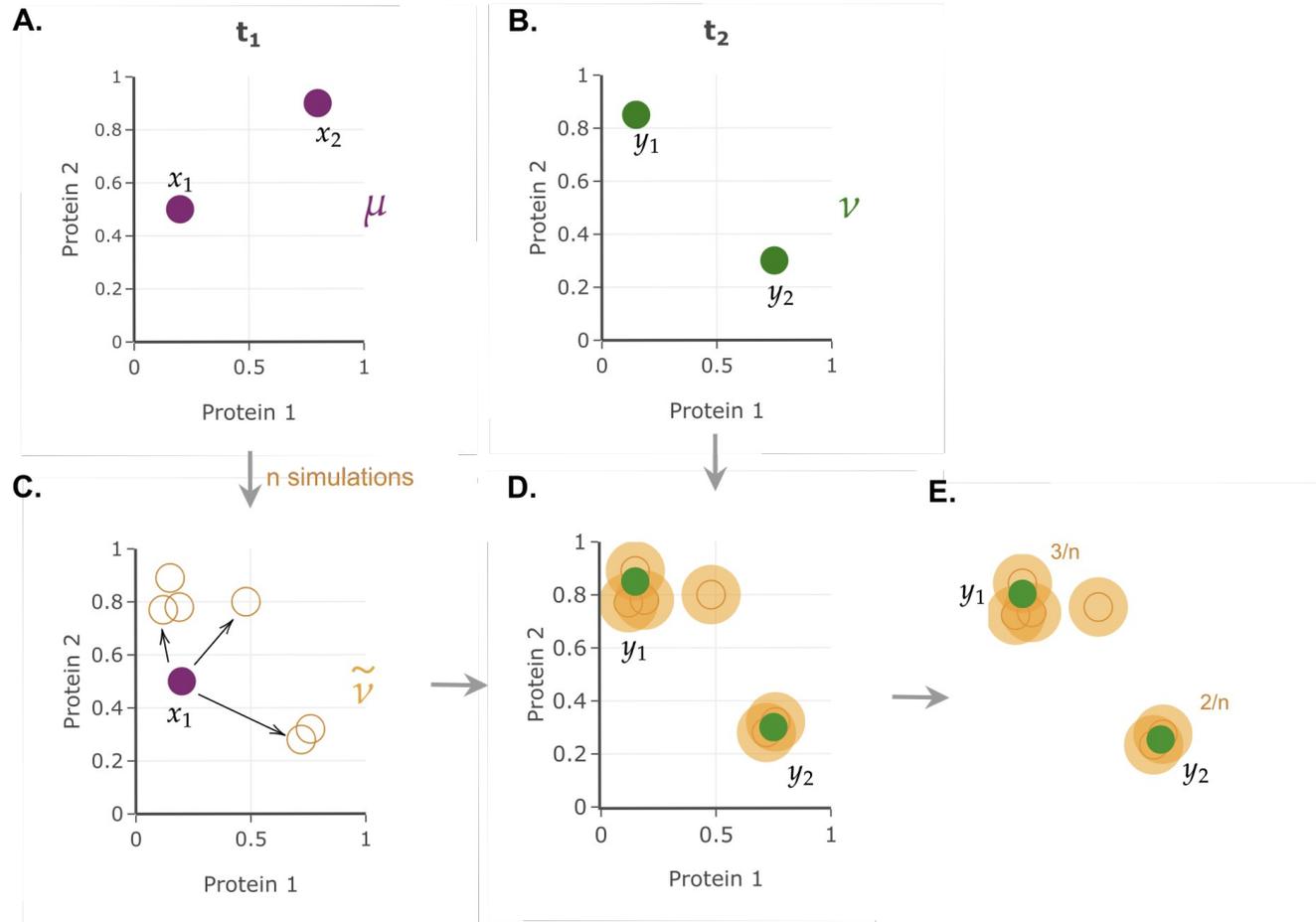
# Methods: Approximation of the reference process



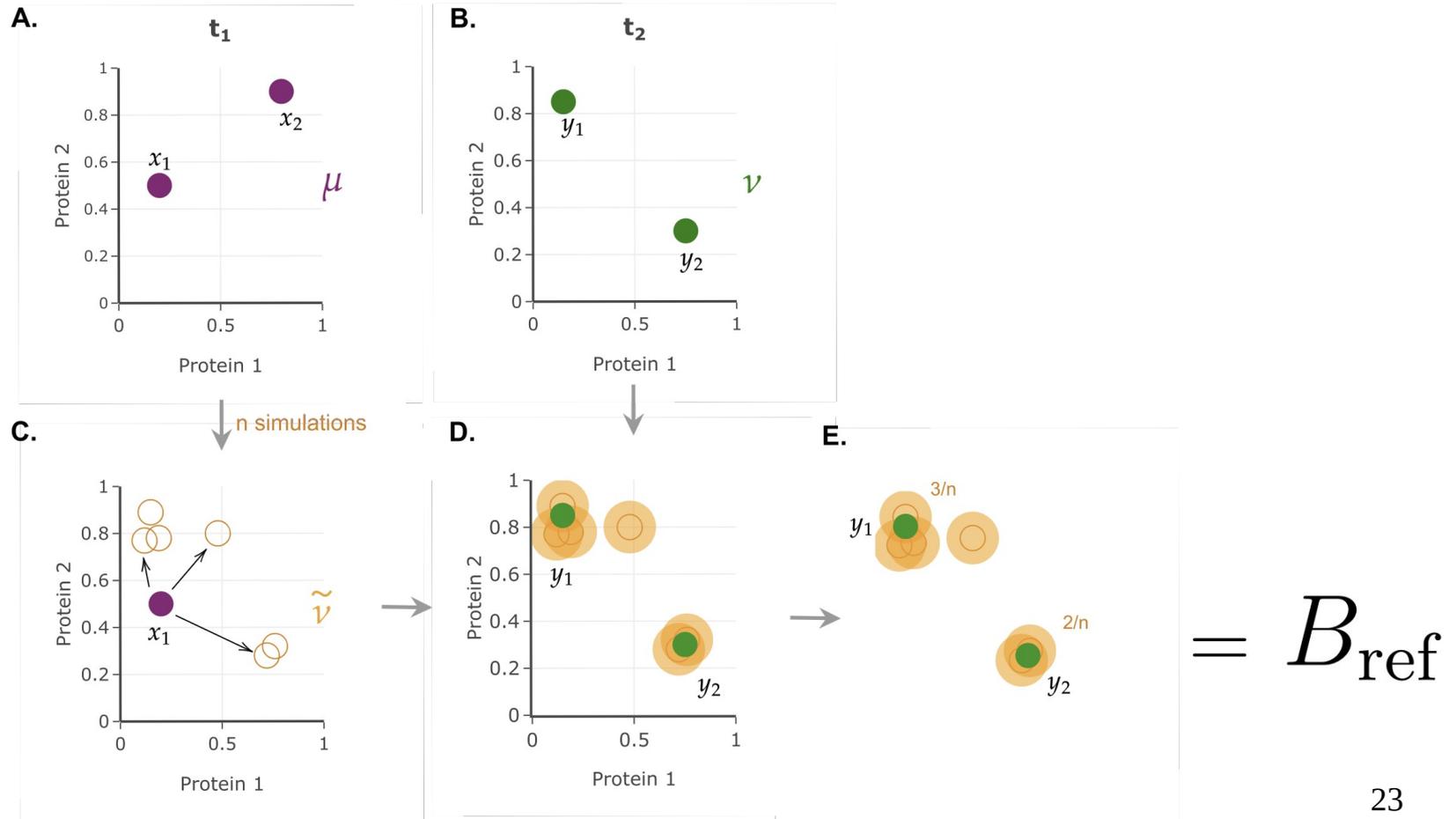
# Methods: Approximation of the reference process



# Methods: Approximation of the reference process



# Methods: Approximation of the reference process



# Methods: Schrödinger Problem

$$B_{\text{sch}} := \arg \min_{Q \in \mathcal{P}(X \times Y)} \{H(Q|B_{\text{ref}}); Q(t_1) = u, Q(t_2) = v\}$$

$$\text{With } H(Q|R) = \sum_{ij} Q_{ij} \log \left( \frac{Q_{ij}}{R_{ij}} \right)$$

# Methods: Schrödinger Problem

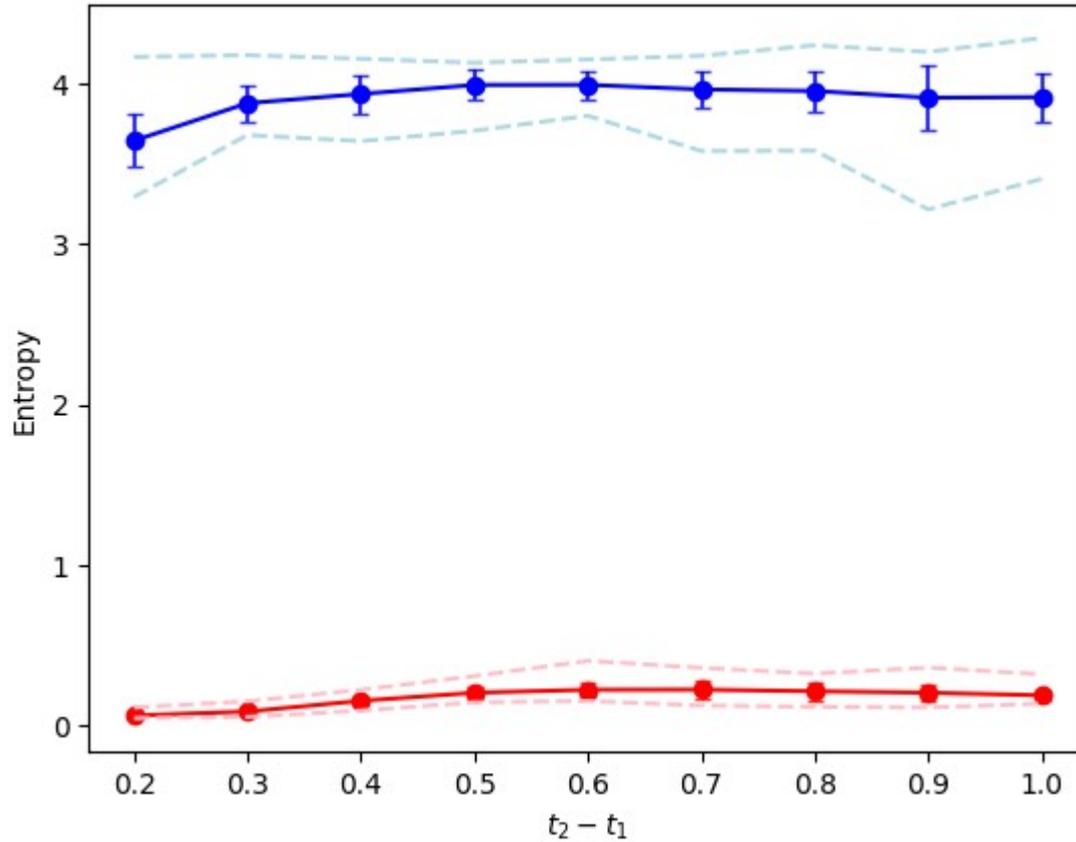
$$D_{\text{sch}} := \arg \min_{Q \in \mathcal{P}(X \times Y)} \{H(Q | D_{\text{ref}}); Q(t_1) = u, Q(t_2) = v\}$$

# Methods: Entropy

$$H_{D,B} := H(D_{\text{sch}} | B_{\text{sch}}),$$

$$H_B := H(B_{\text{ref}} | B_{\text{sch}})$$

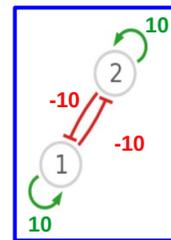
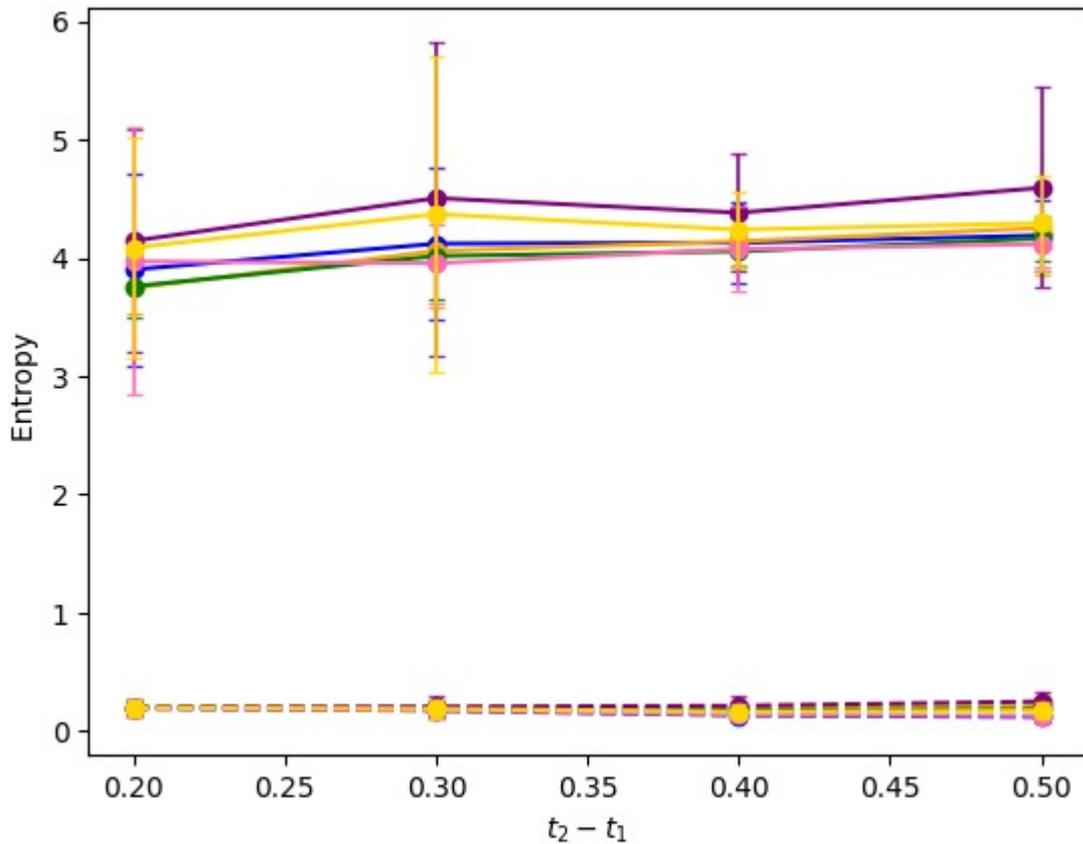
# Results: Entropy



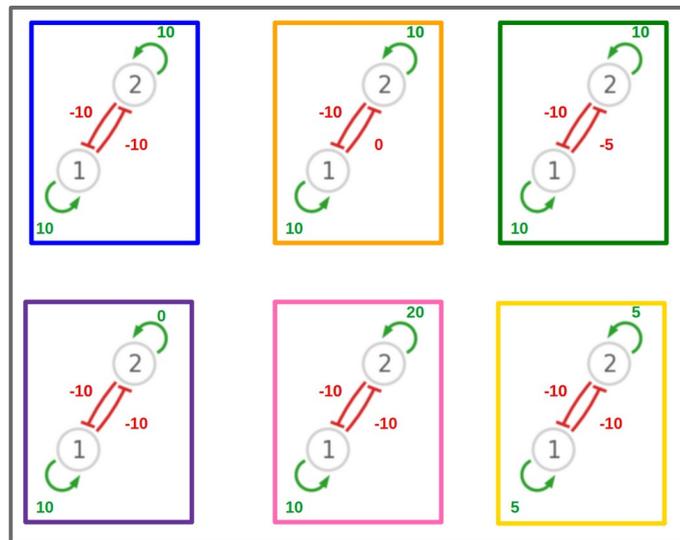
$$H_{D,B} := H(D_{\text{sch}} | B_{\text{sch}})$$

$$H_B := H(B_{\text{ref}} | B_{\text{sch}})$$

# Results: Entropy



$\mu$  and  $\nu$



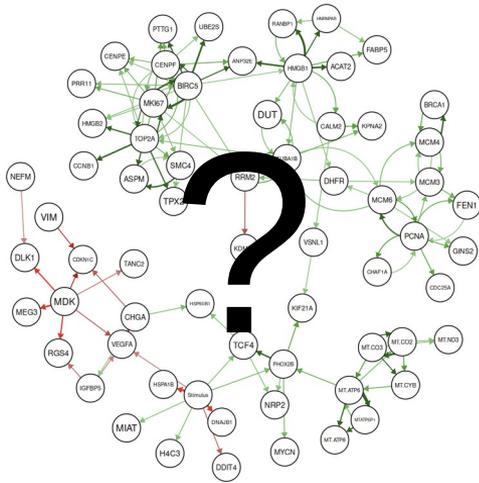
$B_{\text{ref}}$

# Discussion

How to extend the model for real data ?

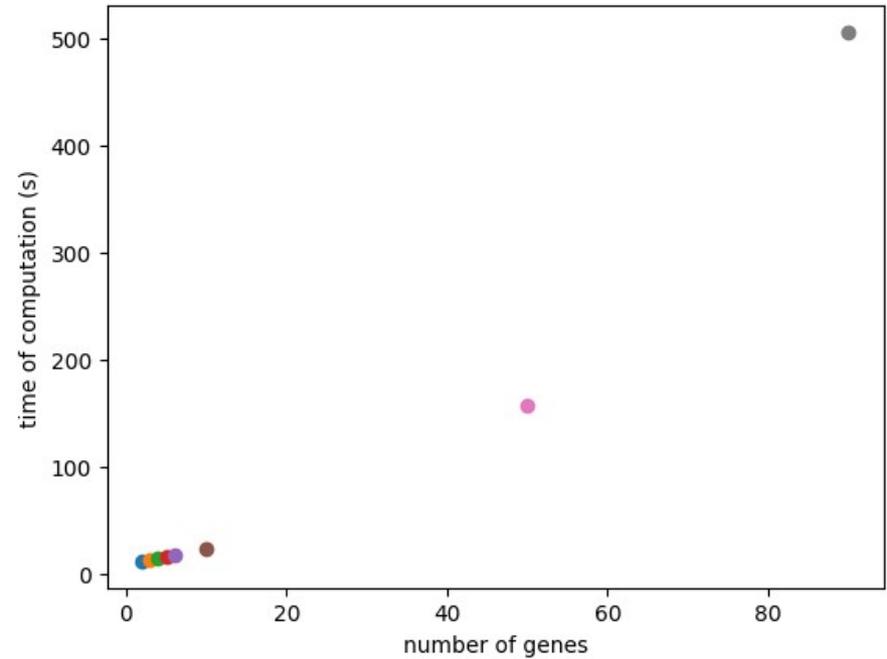
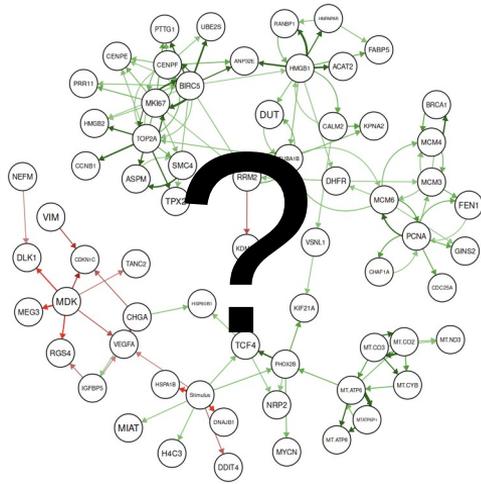
# Discussion

How to extend the model for real data ?



# Discussion

How to extend the model for real data ?



# Discussion : Next steps

